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ORIGINAL ARTICLE

T-proximity compatible with T-neighbourhood structure

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KEYWORDS

Triangular norm; *T*-neighbourhood spaces; *T*-proximity spaces **Abstract** In this paper, we show that every *T*-neighbourhood space induces a *T*-proximity space, where *T* stands for any continuous triangular norm. An axiom of *T*-completely regular of *T*-neighbourhood spaces introduced by Hashem and Morsi (2003) [3], guided by that axiom we supply a Sierpinski object for category *T*-PS of *T*-proximity spaces. Also, we define the degree of functional *T*-separatedness for a pair of crisp fuzzy subsets of a *T*-neighbourhood space. Moreover, we define the Čech *T*-proximity space of a *T*-completely regular *T*-neighbourhood space, hence, we establishes it is the finest *T*-proximity space which induces the given *T*-neighbourhood space.

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1. Introduction

In [2], Hashem and Morsi deduced the *T*-neighbourhood spaces, for each continuous triangular norm *T*. In this manuscript, we introduce for a given *T*-neighbourhood space, a new structure of functional *T*-separatedness, which generates a *T*-proximity space. Moreover, we show that the existence of correspondence between *T*-proximity and *T*-neighbourhood structure is fulfilled. Also, we define the Čech *T*-proximity space for a *T*-neighbourhood space, we establish that it is the finest *T*-proximity space which generates the given *T*-neighbourhood space. We divided this manuscript into four sections:

In the first section, we recapitulate on some definitions and ideas of fuzzy sets, *T*-proximity spaces and *T*-uniform spaces.

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In the second section, we introduce five propositions, which well be used to supply the notion of a Sierpinski object for category *T*-PS of *T*-proximity spaces.

In the third section, we introduce the definition and properties of functional *T*-separatedness of crisp fuzzy subsets for a *T*-neighbourhood space, together with an illustrative example for this notion.

In the fourth section, we complete the proof of the compatibility between *T*-proximity spaces and *T*-neighbourhood spaces. Also, we introduce the notion of Čech *T*-proximity space.

2. Prerequisites

In this section we will recall some of the definitions related to fuzzy sets, *T*-proximity spaces, *T*-uniform spaces and *I*-topological spaces.

A triangular norm (cf. [10]) is a binary operation on the unit interval I = [0, 1] that is associative, symmetric, monotone in each argument and has the neutral element 1.

A fuzzy set λ in a universe set X, introduced by Zadeh in [11], is a function $\lambda : X \to I$. The collection of all fuzzy sets

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of X is denoted by I^X . The height of a fuzzy set λ is the following real number: $hgt\lambda = sup\{\lambda(x): x \in X\}$.

If *H* is a subset of *X*, then we shall denote to its characteristic function by the symbol $\mathbf{1}_H$, said to be a crisp fuzzy subset of *X*. We also denote the constant fuzzy set of *X* with value $\alpha \in I$ by $\underline{\alpha}$.

Given a fuzzy set $\lambda \in I^X$ and a real number $\alpha \in I_1 = [0, 1[$, the strong α -cut of λ is the following subset of X: $\lambda^{\alpha} = \{x \in X : \lambda(x) > \alpha\}$; and the weak α -cut of λ is the subset of X: $\lambda_{\alpha^*} = \{x \in X : \lambda(x) \ge \alpha\}$.

For a given two fuzzy sets $\mu, \lambda \in I^X$ we denote by $\mu T \lambda$ the following fuzzy set of X: $(\mu T \lambda)(x) = \mu(x)T\lambda(x), x \in X$.

We follow Lowen's definition of a fuzzy closure operator on a set X [7]. This is an operator ${}^-:I^X \to I^X$ that satisfies $\mu^- \ge \mu, (\mu \bigvee \lambda)^- = \mu^- \bigvee \lambda^-$ for all $\mu, \lambda \in I^X$, and $\underline{\alpha}^- = \underline{\alpha}$ for all $\alpha \in I$. We may define an *I*-topology in the usual way, namely assuming a fuzzy set μ to be closed if and only if $\mu^- = \mu$. We denote this *I*-topology by τ . The pair (X, τ) is called an *I*-topological space. A function $f: (X, -) = (X, \tau)$ $\to (Y, -') = (Y, \tau')$, between two *I*-topological spaces, is said to be continuous [7]; if $f^{\leftarrow}(\mu) \in \tau$, for all $\mu \in \tau'$, equivalently if $f(\lambda^-) \leq [f(\lambda)]^{-\prime}$, for all $\lambda \in I^X$.

I-filters and *I*-filterbases were introduced by Lowen in [8]. An *I*-filter in a universe *X* is a nonempty collection $\mathfrak{I} \subset I^X$ which satisfies: $\underline{0} \notin \mathfrak{I}$, \mathfrak{I} is closed under finite meets and contains all the fuzzy supersets of its individual members. An *I*-filterbase in *X* is a nonempty collection $\mathcal{B} \subset I^X$ which satisfies: $\underline{0} \notin \mathcal{B}$ and the meet of two members of \mathcal{B} contain a member of \mathcal{B} .

The *T*-neighbourhood spaces and *T*-proximity spaces were introduced by Hashem and Morsi, for more definitions and properties, we can refer to [1,2].

Definition 2.1 [2]. A *T*-neighbourhood space is an *I*-topological space $(X, \tau) = (X, \overline{})$ whose fuzzy closure operator $\overline{}$ is induced by some indexed family $\mathcal{B} = (\mathcal{B}(x))_{x \in X}$ of *I*-filterbases on I^X , in the following manner: For all $\mu \in I^X$ and $x \in X$, $\mu^-(x) = \inf_{v \in \mathcal{B}} hgt(\mu T v)$.

Theorem 2.1 [1]. A function $\delta: I^X \times I^X \to I$ is a T-proximity on a set X if and only if it satisfies the following six axioms, the first five of which are properties of its restriction $\delta: 2^X \times 2^X \to I$. For all $H, M, N \in 2^X$:

 $\begin{array}{ll} (\mathrm{TP1}) & \delta(\mathbf{1}_{\emptyset},\mathbf{1}_{X}) = 0; \\ (\mathrm{TP2}) & \delta(\mathbf{1}_{H},\mathbf{1}_{M}) = \delta(\mathbf{1}_{M},\mathbf{1}_{H}); \\ (\mathrm{TP3}) & \delta(\mathbf{1}_{(H\cup M)},\mathbf{1}_{N}) = \delta(\mathbf{1}_{H},\mathbf{1}_{N}) \bigvee \delta(\mathbf{1}_{M},\mathbf{1}_{N}); \\ (\mathrm{TP4}) & If \ \delta(\mathbf{1}_{H},\mathbf{1}_{M}) < (\theta T\beta) \ for \ some \ \theta,\beta \in I_{I}, \ there \ is \\ & C \in 2^{X} \ such \ that \ \delta(\mathbf{1}_{H},\mathbf{1}_{C}) \leqslant \theta \ and \\ & \delta(\mathbf{1}_{(X-C)},\mathbf{1}_{M}) \leqslant \beta; \\ (\mathrm{TP5}) & If \ H \cap M \neq \emptyset, \ then \ \delta(\mathbf{1}_{H},\mathbf{1}_{M}) = I; \\ (\mathrm{TP6}) & \delta(\mu,\lambda) = \bigvee_{\theta,\beta \in I} [\theta T\beta T\delta(\mathbf{1}_{\mu_{\theta k}},\mathbf{1}_{\lambda_{\beta k}})], \ \mu,\lambda \in I^{X}. \end{array}$

The real number $\delta(\mathbf{1}_H, \mathbf{1}_M)$ can be interpreted as the degree of proximity between the two crisp fuzzy subsets $\mathbf{1}_H$ and $\mathbf{1}_M$, and the number $\delta(\mu, \lambda)$ can be interpreted as the degree of nearness of the fuzzy sets μ and λ . The pair (X, δ) is said to be a *T*-proximity space.

A function $f : (X, \delta) \rightarrow (Y, \rho)$ between two *T*-proximity spaces, is said to be continuous, if

$$\delta(\mu,\lambda) \leqslant \rho(f(\mu),f(\lambda)), \quad \forall \ \mu,\lambda \in I^X.$$
(1)

This is shown in [1], to be equivalent to

$$\delta(\mathbf{1}_H, \mathbf{1}_M) \leqslant \rho(f(\mathbf{1}_H), f(\mathbf{1}_M)), \quad \forall \mathbf{H}, \mathbf{M} \in 2^X.$$
(2)

Given two *T*-proximities δ_1 , δ_2 on *X*, δ_1 is said to be coarser than δ_2 (δ_2 is said to be finer than δ_1), if the identity function on *X* is a proximally continuous from (*X*, δ_2) to (*X*, δ_1), that is $\delta_2(\mathbf{1}_H, \mathbf{1}_M) \leq \delta_1(\mathbf{1}_H, \mathbf{1}_M)$, for every pair of crsip fuzzy sets $H, M \subset X$.

In [5], Höhle defines for every $\psi, \varphi \in I^{X \times X}$ and $\lambda \in I^X$: The *T*-section of ψ over λ by $(\psi(\lambda)_T)(x) = \sup_{z \in X} [\lambda(z)T\psi(z,x)]$, $x \in X$. The *T*-composition of ψ , φ by $(\psi \circ_T \varphi)(x,y) = \sup_{z \in X} [\varphi(x,z)T\psi(z,y)]$, $x, y \in X$. Also, in [5], Höhle defines the (fuzzy) *T*-uniform spaces and uniformly continuous of a function $f: (X, \Omega) \to (Y, \varpi)$, between *T*-uniform spaces, as for every $\varphi \in \varpi$ there is $\psi \in \Omega$ such that $\psi \leq (f \times f)^{\leftarrow}(\varphi)$.

A functor from category *T*-US of *T*-uniform spaces to category *T*-PS of *T*-proximity spaces is obtained in [1], by leaving morphisms unchanged, and by sending $(X, \Omega) \in T$ -US to the *T*-proximity space $(X, \delta(\Omega))$ given by

$$(\delta(\Omega))(\mu,\lambda) = \inf_{\psi \in \Omega} \sup_{y \in X} (\mu T \psi \langle \lambda \rangle_T)(y), \quad \mu, \lambda \in I^X.$$
(3)

Another functor from category *T*-PS to category *I*-TS of *I*-topological spaces is obtained in [2], by leaving morphisms unchanged and by sending $(X, \delta) \in T$ -PS to the *I*-topological space $(X, \tau(\delta))$ with the fuzzy closure operator:

$$\mu^{-}(x) = \delta(\mu, \mathbf{1}_{x}), \quad \mu \in I^{X}, \ x \in X.$$
(4)

In [2], this *I*-topological space $(X, \tau(\delta))$ is shown to be a *T*-neighbourhood space. By applying these two functors to the identity function on *X*, we find that if Ω_1, Ω_2 are *T*-uniformities on *X* and $\Omega_1 \subseteq \Omega_2$, then $\delta(\Omega_2)$ is coarser than $\delta(\Omega_1)$, while if δ_1 , δ_2 are *T*-proximities on the set *X*, and δ_1 is coarser than δ_2 , then $\tau(\delta_1) \subseteq \tau(\delta_2)$.

3. A Sierpinski object for the category T-PS

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A distance distribution function (ddf) [10], is a function from the set R^+ of positive real numbers to the unit interval *I*, which is isotone, left continuous and has supremum 1. The set of all ddf's is denoted by \mathcal{D} . The partial order \leq on \mathcal{D} is the opposite of the partial order of ddf's as real functions. Obviously (\mathcal{D}, \leq) is a lattice, we denote its join by \sqcup , and its meet by \sqcap . The set R^* of nonnegative real numbers, can be embedded in (\mathcal{D}, \leq) by sending every $r \geq 0$ onto the crisp ddf ε_r given by

$$\begin{aligned} & \begin{bmatrix} 0, & 0 < s \leqslant \\ \varepsilon_r(s) = \\ & 1, & s > r. \end{aligned}$$

In particular, $\varepsilon_0 =$ the constant function 1 on R^+ , is the bottom element of (\mathcal{D}, \preceq) . The *T*-addition \oplus_T and scaler multiplication by nonnegative reals are defined on \mathcal{D}^+ as follows: for $\eta, \zeta \in \mathcal{D}^+$ and s > 0:

$$(\eta \oplus_T \zeta)(s) = \sup\{\eta(b)T\zeta(s-b) : 0 < b < s\}.$$
(5)

$$(b\eta)(s) = \eta(s/b), \text{ for any } b > 0.$$
 (6)

Definition 3.1. [10]A probabilistic *T*-metric (*T*-PM) on a set *X* is a function $\mp : X \times X \to \mathcal{D}^+$ that satisfies, for all $x, y, z \in X$:

(TPM1)
$$\mp(x, x) = 0;$$

(TPM2) $\mp(x, y) = \mp(y, x);$

The pair (X, \mp) is called a probabilistic *T*-metric space. If \mp satisfies (TPM1)–(TPM3) only, then \mp is called a probabilistic *T*-pseudometric.

We shall apply the following notation: Given two nonempty subsets H, M of a probabilistic T-metric space (X, \mp) , we put

$$\mp(H,M) = \{\mp(x,y) : (x,y) \in H \times M\}.$$
(7)

A function $F_H: X \to \mathcal{D}^+$ is defined by

$$F_H = \mp(H, x). \tag{8}$$

Also, for $\eta \in \mathcal{D}^+$, we write

$$\eta(0+) = \inf_{r>0} \eta(r).$$
(9)

Theorem 3.1. [3] Let (X, \mp) be a probabilistic *T*-metric space. Then the *T*-proximity $\delta = \delta(\mp)$, induced by \mp , is given by:

$$\delta(\mu,\lambda) = \inf_{r>0} \sup_{x,y\in X} \{\mu(x)T(\mp(x,y))(r)T\lambda(y)\}, \quad \mu,\lambda\in I^X.$$

In particular, $\delta(\mathbf{1}_H, \mathbf{1}_M) = (\mp (H, M))(0+)$, $H, M \in 2^X$.

Consequently, the fuzzy closure operator $\overline{}$ of the T-neighbourhood space $(X, \tau(\mp))$ is given by:

$$\mu^{-}(x) = \inf_{r>0} \sup_{y \in X} [\mu(y) \ T(\mp(x, y))(r)], \quad \mu \in I^{X}, \ x \in X$$

In particular, $(\mathbf{1}_{H})^{-}(x) = (\mp (H, x))(0+), H \in 2^{X}, x \in X.$

For each triangular norm T, Höhle introduced in [4] a probabilistic T-metric on \mathcal{D}^+ , which we denote by \mathfrak{I} , as follows: for all $\eta, \zeta \in \mathcal{D}^+$,

$$\mathfrak{I}(\eta,\zeta) = \sqcap \{\xi \in \mathcal{D}^+ : \eta \preceq \zeta \oplus_T \xi \text{ and } \zeta \preceq \eta \oplus_T \xi \}.$$
(10)

Obviously, it follows at once that [5]:

$$\Im(\eta, \varepsilon_0) = \eta, \quad \forall \ \eta \in \mathcal{D}^+.$$
(11)

In [4–6], Höhle defines for a T-PM \mp on a set X, a T-uniformity $\Omega(\mp)$ on X by its T-uniform base $\{\psi_r \in I^{X \times X}: r > 0\}$, where

$$\psi_r(x,y) = (\mp(x,y))(r), \quad x,y \in X.$$
 (12)

Proposition 3.1. [10]*In* (\mathcal{D}^+ , $\Omega(\mathfrak{I})$), the binary operations \sqcup , \sqcap , \oplus_T are uniformly continuous. Also, scaler multiplication on \mathcal{D}^+ by a fixed $b \ge 0$ is uniformly continuous. In consequence, if $f, g: X \to \mathcal{D}^+$ are two (uniformly) continuous functions, then so will be $f \sqcup g, f \sqcap g, f \oplus_T g, bf$.

Proposition 3.2. Let M be a nonempty subset of X and $f: X \to (\mathcal{D}^+, \tau(\mathfrak{I}))$ be a function such that $f(M) = \varepsilon_0$. Then for all $x \in X$, we have $[f(M)]^-(f(x)) = (f(x))(0+)$.

Proof 1. For every
$$x \in X$$
, we have
 $(f(x))(0+) = \Im(f(x), \varepsilon_0)(0+), \quad \text{by}(11)$
 $= \Im(\varepsilon_0, f(x))(0+), \quad \text{by} \text{ (TPM2)}$
 $= (\varepsilon_0)^-(f(x)), \quad \text{by Theorem 3.1}$
 $= [f(M)]^-(f(x)). \quad \Box$

Definition 3.2. [3]A *T*-neighbourhood space (X, Σ) is said to be *T*-completely regular if its *I*-topology Σ equals the initial *I*-topology for the family of all continuous functions: $(X, \Sigma) \to (\mathcal{D}^+, \tau(\mathfrak{I})).$

Theorem 3.2. [3]Let $(X, -) = (X, \Sigma)$ be a *T*-neighbourhood space. Then, the following statements are equivalent:

- (i) (X, -) is T-completely regular;
- (ii) (X, -) is *T*-unifomizable;
- (iii) For every $M \subseteq X$, $x \in X$ and $\theta \in I_0$, there is a continuous function

$$f: (X, {}^{-}) \to (\mathcal{D}^+, \tau(\mathfrak{Z})) \text{ such that} f(M) = \varepsilon_0 \quad \text{and}$$
$$(f(x))(0+) < (\mathbf{1}_M)^-(x) + \theta.$$
(13)

In categorical terms, Theorem 3.2 says that $(\mathcal{D}^+, \tau(\mathfrak{I}))$ is a Sierpinski object for the full subcategory of *T*-NS, of *T*-uniformizable *T*-neighbourhood spaces. For a brief introduction to topological categories and Sierpinski objects, see [9]. Now, we proceed to supply a Sierpinski object for category *T*-PS.

Definition 3.3. A gauge for a *T*-uniformity Ω on a set *X* is a *T*-PM \mp on *X* such that $\Omega(\mp) \subseteq \Omega$.

Proposition 3.3. Let ψ be a fuzzy vicinity in a *T*-uniform space (X, Ω) . Then there is a gauge \mp for Ω such that $\psi \in \Omega(\mp)$.

Proof 2. We can choose a decreasing sequence $(\psi_{n-1})_{n \in N}$ of symmetric members of Ω , such that $\psi_0 \leq \psi$ and $(\psi_n \ o_T \ \psi_n \ o_T \ \psi_n) - 2^{-n} \leq \psi_{n-1}$.

Define $F: X \times X \to \mathcal{D}^+$ as follows:

$$\begin{aligned} & [0, & s = 0\\ (F(x, y))(s) &= |\psi_k(x, y), & 2^{-k} < s \leq 2^{-(k-1)}\\ & |1, & s > 1. \end{aligned}$$

Next, define $\mp : X \times X \to \mathcal{D}^+$, by

$$\mp(x,y) = \bigvee \left\{ \bigoplus_{i=1}^{n} F(x_{i-1},x_i) : x_i \in X, x_0 = x, x_n = y, n \in N \right\}.$$

It is easy to see that \mp is a probabilistic *T*-pseudometric with $\Omega(\mp) \subseteq \Omega$, also

 $\psi_{n+1}(x,y) \leq (\mp(x,y))2^{-n} \leq \psi_n(x,y) + 2^{-n}.$

Now, for every $\varepsilon > 0$, choose $n \in N$ such that $\epsilon > 2^{-n}$, we get $(\overline{-(\alpha, \alpha)})(2^{-n}) = \varepsilon \in d_{\varepsilon}(\alpha, \alpha) \in c_{\varepsilon}(\alpha, \alpha)$

$$(\mp(x,y))(2^{-n}) - \varepsilon \leqslant \psi_n(x,y) \leqslant \psi(x,y).$$

Which proves that $\psi \in \Omega(\mp)$. \Box

Proposition 3.4. Let (X, Ω) be a T-uniform space. Then for all $\psi \in \Omega$, $\theta \in I_0$, $x \in X$ and a nonempty subset M of X, there is a uniformly continuous function $g : (X, \Omega) \to (\mathcal{D}^+, \Omega(\mathfrak{I}))$ such that $g(M) = \varepsilon_0$ and $(g(x))(1) < (\psi \langle \mathbf{1}_M \rangle_T)(x) + \theta$.

Proof 3. By Proposition 3.3, there is a *T*-PM \mp on *X* with $\psi \in \Omega(\mp) \subseteq \Omega$.

Consequently, $\psi + \frac{1}{2}\theta \ge \psi_1 \in \Omega(\mp)$, where $\psi_1(x, y) = (\mp(x, y))$ (1), $\forall x, y \in X$ (cf.(12)).

Let $F_M: X \to \mathcal{D}^+$ be a function given by

$$F_M(x) = \mp(M, x) = \sup_{y \in M} \mp(y, x), \quad x \in X$$

This F_M is a uniformly continuous [6. Proposition 5.2], also, $F_M(M) = \varepsilon_0$, (by (TPM1)). Thus for every $x \in X$, we have

$$\begin{aligned} (\psi \langle \mathbf{1}_M \rangle_T)(x) + \theta &\ge (\psi_1 \langle \mathbf{1}_M \rangle_T)(x) + \frac{1}{2}\theta \\ &= \left\{ \sup_{y \in X} [\mathbf{1}_M(y)T\psi_1(y,x)] \right\} + \frac{1}{2}\theta \\ &= \sup_{y \in M} \psi_1(y,x) + \frac{1}{2}\theta \\ &> \sup_{y \in M} \mp (y,x)(1) \\ &= (F_M(x))(1). \end{aligned}$$

This shows that F_M satisfies all the properties stated for g. \Box

Proposition 3.5. If (X, δ) is a T-proximity space, then for all nonempty subsets H, M of X and all $\alpha > \delta(\mathbf{1}_H, \mathbf{1}_M)$, there is a proximally continuous function $f: (X, \delta) \to (\mathcal{D}^+, \delta(\mathfrak{I}))$ such that $f(M) = \varepsilon_0$, f is constant on H and $\eta = f(H)$ satisfies $\eta(1) = \alpha$.

Proof 4. There is a *T*-uniformity Ω on *X* that induces δ [1]. Since $\alpha > \delta(\mathbf{1}_H, \mathbf{1}_M)$, then there is, by (3), a fuzzy vicinity $\psi \in \Omega$ such that

 $\sup_{u \in V} (\mathbf{1}_H T \psi \langle \mathbf{1}_M \rangle_T)(y) = \alpha - \theta, \text{ for some } \theta > 0.$

By Proposition 3.4, there is a uniformly continuous function $g: (X, \Omega) \to (\mathcal{D}^+, \Omega(\mathfrak{I}))$ such that $g(M) = \varepsilon_0$ and for all $x \in H$; $g(x)(1) < (\psi \langle \mathbf{1}_M \rangle_T)(x) + \theta \leq (\alpha - \theta) + \theta = \alpha$. Define $\eta \in \mathcal{D}^+$ by

$$\begin{bmatrix} 0, & s = 0 \\ \eta(s) = |\alpha, & 0 < s \leqslant 1 \\ \lfloor 1, & s > 1. \end{bmatrix}$$

Then $\eta \leq g(x)$ for all $x \in H$. Define $f: X \to \mathcal{D}^+$, by $f(x) = g(x) \sqcap \eta, \ \forall x \in X$. Then f is uniformly continuous (by Proposition 3.1) and hence it is a proximally continuous from (X, δ) to $(\mathcal{D}^+, \delta(\mathfrak{I}))$. Also, $f(M) = \varepsilon_0$ and $f(H) = \eta$.

This completes the proof. \Box

Theorem 3.3. Every T-proximity δ on a set X is the initial Tproximity (= optimal lift in T-PS) for the set of all proximally continuous functions from (X, δ) into $(\mathcal{D}^+, \delta(\mathfrak{I}))$. Therefore, the *T*-proximity space $(\mathcal{D}^+, \delta(\mathfrak{I}))$ is a Sierpinski object for the category T-PS.

Proof 5. Let δ_1 be the mentioned initial (coarsest) *T*-proximity on X. Then δ_1 is coarser than δ .

Now, we demonstrate the opposite relationship. Let nonempty subsets $H, M \in 2^X$ and $\alpha \in I$, be such that $\alpha > \delta(\mathbf{1}_H, \mathbf{1}_M).$

Then by Proposition 3.5, there is a proximally continuous function $f: (X, \delta) \to (\mathcal{D}^+, \delta(\mathfrak{I}))$ that satisfies $f(M) = \varepsilon_0$, f is constant on H, and $\eta = f(H)$ has $\eta(1) = \alpha$. By definition of δ_1 , *f* is also a proximally continuous from (X, δ_1) into $(\mathcal{D}^+, \delta(\mathfrak{I}))$. Consequently,

$$\begin{split} \delta_1(\mathbf{1}_H, \mathbf{1}_M) &\leqslant (\delta(\mathfrak{I}))(f(\mathbf{1}_H), (f\mathbf{1}_M)), \quad \text{by (2)} \\ &= \delta(\mathfrak{I}))(\mathbf{1}_{f(H)}, \mathbf{1}_{f(M)}), \quad \text{clear} \\ &= \mathfrak{I}(f(H), f(M))(0+), \quad \text{by Theorem 3.1} \\ &= \mathfrak{I}(\eta, \varepsilon_0)(0+) \\ &= \eta(0+), \quad \text{by (11)} \\ &\leqslant \eta(1), \quad \text{by isotonicity of } \eta \\ &= \alpha. \end{split}$$

This establishes that $\delta_1(\mathbf{1}_H, \mathbf{1}_M) \leq \delta(\mathbf{1}_H, \mathbf{1}_M)$ for all $H, M \in X$, that is δ is coarser than δ_1 . Therefore, $\delta = \delta_1$, as required. \Box

4. Functional T-separatedness

In this section, we introduce the definition and some properties of functional T-separatedness of crisp fuzzy subsets for a given T-neighbourhood space.

Definition 4.1. Let (X, Σ) be a *T*-neighbourhood space. For all nonempty subsets H, M of X, let $\Re(H, M) = \Re_{\Sigma}(H, M)$ be the following set of functions:

 $\mathfrak{R}(H, M) = \{f : (X, \Sigma) \to (\mathcal{D}^+, \tau(\mathfrak{I})) : f \text{ is } \}$ continuous, $f(H) = \varepsilon_0$ and f is constant on M.

(This set is nonempty, as it contains the constant function ε_0).

We define a function $\Gamma = \Gamma_{\Sigma}: 2^X \times 2^X \to I$ by

$$\Gamma(\mathbf{1}_{H},\mathbf{1}_{M}) = \sup_{f \in \mathfrak{N}(H,M)} [1 - f(M)(0+)], \quad H, M \in 2^{X}.$$
 (14)

and

$$\Gamma(\mathbf{1}_H, \mathbf{1}_{\emptyset}) = \Gamma(\mathbf{1}_{\emptyset}, \mathbf{1}_H) = 1, \quad H \in 2^X.$$
(15)

The function Γ is said to be functional T-separatedness and the real number $\Gamma(\mathbf{1}_H, \mathbf{1}_M)$ is called the degree of functional T-separatedness of H and M in (X, Σ) .

In the following theorem we compile those properties of the function Γ which we shall need in the next section.

Theorem 4.1. Let (X, Σ) be a *T*-neighbourhood space. Then for all $H, M, N \in 2^X$, we have

- (FTS1) $\Gamma(\mathbf{1}_H, \mathbf{1}_M) = \Gamma(\mathbf{1}_M, \mathbf{1}_H);$
- (FTS2) if $H \subseteq M$, then $\Gamma(\mathbf{1}_H, \mathbf{1}_N) \ge \Gamma(\mathbf{1}_M, \mathbf{1}_N)$;
- (FTS3) $\Gamma(\mathbf{1}_{(H\cup M)}, \mathbf{1}_N) = \Gamma(\mathbf{1}_H, \mathbf{1}_N) \wedge \Gamma(\mathbf{1}_M, \mathbf{1}_N);$
- (FTS4) If $\Gamma(\mathbf{1}_{H},\mathbf{1}_{M}) > 1 (\theta T \beta)$ for some $\theta, \beta \in I_{0}$, there is $C \in 2^{X}$ such that $\Gamma(\mathbf{1}_{H},\mathbf{1}_{C}) > 1 \theta$ and $\Gamma(\mathbf{1}_{(X-C)},\mathbf{1}_M) > 1-\beta;$

(TP5) If $H \cap M \neq \emptyset$, then $\Gamma(\mathbf{1}_H, \mathbf{1}_M) = 0$;

Proof 6. These are easily seen to hold whenever one of the entering sets is empty. So, suppose that H, M and N are nonempty subsets of X, then

(FTS1) For all $f \in \mathfrak{R}(H, M)$, define $g_f: X \to \mathcal{D}^+$, by $g_f(x) = \Im(f(x), f(M)), \quad x \in X.$

Then for all $x \in H$, we get

$$g_f(x) = \Im(\varepsilon_0, f(M))$$

= $\Im(f(M), \varepsilon_0)$, by (TPM2)
= $\Im f(M)$, by (12)

that is, $g_f(H) = f(M)$.

Since f is constant on M, then, for all $y \in M$, we have $g_f(y) = \Im(f(y), f(M)) = \varepsilon_0$.

Moreover, g_f equals the composite function $\Im o(f \times (f(M)))$, where f(M) is constant ddf. and \times restricted cartesian product of functions. Since these three functions are continuous (cf. [3]), we conclude that g_f is also continuous, therefore g_f is in $\Re(M, H)$. Consequently,

$$\begin{split} \Gamma(\mathbf{1}_{H},\mathbf{1}_{M}) &= \sup_{f \in \Re(H,M)} [1 - f(M)(0+)] \\ &= \sup_{f \in \Re(H,M)} [1 - g_{f}(H)(0+)] \\ &\leqslant \sup_{g \in \Re(M,H)} [1 - g(H)(0+)] \\ &= \Gamma(\mathbf{1}_{M},\mathbf{1}_{H}). \end{split}$$

Hence equality holds by interchanging H and M.

(FTS2) if $H \subseteq M$, then evidently $\Re(H, N) \supseteq \Re(M, N)$ and so $\Gamma(\mathbf{1}_H, \mathbf{1}_N) \ge \Gamma(\mathbf{1}_M, \mathbf{1}_N)$.

(FTS3) For all $f \in \mathfrak{R}(H, N)$ and $g \in \mathfrak{R}(M, N)$, $f \sqcap g$ is ε_0 on $H \cup M$ and is constant on N. It is also continuous (Proposition 3.1). Therefore, $f \sqcap g$ is also in $\mathfrak{R}(H \cup M, N)$. Hence we obtain

$$\begin{split} \Gamma(\mathbf{1}_{(H\cup M)},\mathbf{1}_N) &= \sup_{h\in\Re(H\cup M,N)} [1-h(N)(0+)] \\ &\geqslant \sup_{(f,g)\in\Re(H,N)\times\Re(M,N)} [1-(f\sqcap g)(N)(0+)] \\ &= \sup_{(f,g)\in\Re(H,N)\times\Re(M,N)} \{1-[f(N)(0+)\bigvee g(N)(0+)]\} \\ &= \sup_{(f,g)\in\Re(H,N)\times\Re(M,N)} \{[1-f(N)(0+)]\bigwedge [1-g(N)(0+)]\} \\ &= \{\sup_{f\in\Re(H,N)} [1-f(N)(0+)]\} \bigwedge \{\sup_{g\in\Re(M,N)} [1-g(N)(0+)]\} \\ &= \Gamma(\mathbf{1}_H,\mathbf{1}_N) \bigwedge \Gamma(\mathbf{1}_M,\mathbf{1}_N). \end{split}$$

The opposite inequality follows from (FTS2). Which renders (FTS3).

(FTS4) Suppose that $\Gamma(\mathbf{1}_H, \mathbf{1}_M) > 1 - (\theta T \beta)$ for some $\theta, \beta \in I_0$, then there are $\alpha, \gamma \in I_0$ and $f_1 \in \mathfrak{R}(H, M)$ such that $[1 - f_1(M)(0 +)] = \alpha > \gamma > 1 - (\theta T \beta)$.

Let $\zeta \in \mathcal{D}^+$ be the ddf defined by

$$\begin{aligned} & \lceil 0, \qquad s = 0 \\ \zeta(s) = |1 - \gamma, \qquad 0 < s \leqslant 1 \\ & |1, \qquad s > 1. \end{aligned}$$

Define $f: X \to \mathcal{D}^+$ by, $f(x) = f_1(x) \sqcap \zeta$, $\forall x \in X$. Then $f(H) = \varepsilon_0$, $f(M) = \zeta$ and f is continuous, by Proposition 3.1. Take $C = \{x \in X: f(x)(1) \leq 1 - \alpha\}$, and let $\eta \in \mathcal{D}^+$ be the ddf

$$\begin{array}{ll} \lceil 0, & s = 0 \\ \eta(s) = |1 - \alpha, & 0 < s \leqslant 1 \\ |1, & s > 1. \end{array}$$

Define $h: X \to D^+$ by, $h(x) = f(x) \sqcap \eta$, $\forall x \in X$. Then $h(H) = \varepsilon_0$, f is continuous and for all $x \in C$, we have, at $s \in [0, 1]$:

$$(h(x))(s) = (f(x) \sqcap \eta)(s)$$

= $(f(x))(s) \bigvee \eta(s)$
 $\geq \eta(s)$
= $1 - \alpha$
= $(f(x))(1) \bigvee (1 - \alpha)$
 $\geq (f(x))(s) \bigvee \eta(s)$, because $f(x)$ is isotone
= $(h(x))(s)$.

Moreover, at s > 1:

 $(h(x))(s) = (f(x) \sqcap \eta)(s) = (f(x))(s) \bigvee \eta$ $(s) = (f(x))(s) \bigvee 1 = 1 = \eta(s)$. Also, $(h(x))(0) = (f(x) \sqcap \eta)(0) = f(x)(0) \bigvee \eta(0) = (f_1(x) \sqcap \zeta)(0) \bigvee \eta(0) = f_1(x)(0) \bigvee \zeta(0) \bigvee \eta(0) = 0$. This proves that $h(C) = \eta$, which completes the proof that h is in $\Re(H, C)$. Consequently,

$$\Gamma(\mathbf{1}_H, \mathbf{1}_C) \ge 1 - h(C)(0+) = 1 - \eta(0+) = \alpha > 1 - (\theta T \beta)$$
$$\ge 1 - \theta;$$

which establishes one half of (FTS4).

Now, define a function $g: X \to \mathcal{D}^+$ by, $g(x) = \Im(\eta, \eta \sqcup \Im(\zeta, \zeta \sqcap \frac{1}{2} f(x)), x \in X.$

We have g is continuous because f, \Box , \Box and \Im are continuous with respect to τ and $\tau(\Im)$.

We need the following identities, which easily follow from definitions of η , ζ and \Im :

$$\mathfrak{I}(\zeta,\eta\oplus_T\zeta)=\eta\tag{16}$$

$$\Im\left(\zeta, \frac{1}{2}\zeta\right) = \zeta \tag{17}$$

$$\mathfrak{F}(\eta,\zeta) = \zeta \tag{18}$$

Thus for every $y \in M$, we get

$$g(y) = \Im(\eta, \eta \sqcup \Im\left(\zeta, \zeta \sqcap \frac{1}{2}\zeta\right)$$

= $\Im(\eta, \eta \sqcup \Im\left(\zeta, \frac{1}{2}\zeta\right)$, because $\frac{1}{2}\zeta \preceq \zeta$
= $\Im(\eta, \eta \sqcup \zeta)$, by (17)
= $\Im(\eta, \zeta)$, because $\eta \preceq \zeta$
= ζ , by (18)

That is, $g(M) = \zeta$. Now, for all $s \ge 0$, we have

$$(\eta \oplus_T \zeta)(s) = \begin{cases} 0, & s = 0\\ |(1-\alpha)T(1-\gamma), & 0 < s \le 1\\ |1-\alpha, & 1 < s \le 2\\ \lfloor 1, & s > 2. \end{cases}$$

Thus,

$$\zeta \preceq \eta \oplus_T \zeta. \tag{19}$$

Hence, for all $x \in X - C$, we get

$$\varepsilon_0 \leq g(x) = \Im(\eta, \eta \sqcup \Im\left(\zeta, \zeta \sqcap \frac{1}{2}f(x)\right)$$

$$\leq \Im(\eta, \eta \sqcup \Im(\zeta, \eta \oplus_T \zeta)), \quad \text{by (19)and definition of } \Im$$

$$= \Im(\eta, \eta \sqcup \eta), \quad \text{by (16)}$$

$$= \Im(\eta, \eta) = \varepsilon_0$$

that is, $g(X - C) = \varepsilon_0$.

Which completes the proof that g is in $\Re(X - C, M)$. In consequence,

 $\Gamma(\mathbf{1}_{(X-C)}, \mathbf{1}_{M}) \ge 1 - g(M)(0+) = 1 - \zeta(0+) = \gamma > 1 - (\theta T \beta) \ge 1 - \beta,$

which establishes the other half of (FTS4).

(FTS5) If $H \cap M \neq \emptyset$, then evidently, every f in $\Re(H, M)$ must be equal to ε_0 on M. Hence,

 $\Gamma(\mathbf{1}_H, \mathbf{1}_M) = \sup_{f \in \Re(H, M)} [1 - f(M)(0+)] = 1 - \varepsilon_0(0+) = 1 - 1 = 0.$

Which completes the proof. \Box

Lemma 4.1. If $(X, {}^{-})$ is a *T*-neighbourhood space, then for all $\mu \in I^X$ and $H \subseteq X$, we have $\mu T (\mathbf{1}_H)^- \leq (\mu T \mathbf{1}_H)^-$.

Proof 7. Let $\mu \in I^X$ and $H \subseteq X$. Then for every $x \in X$, we have $[\mu T(\mathbf{1}_H)^-](x) = \mu(x)T(\mathbf{1}_H)^-(x)$

 $= \mu(x)T \inf_{v \in \Sigma(x)} \operatorname{hgt}(\mathbf{1}_H T v)$ = $\inf_{v \in \Sigma(x)} \operatorname{hgt}[\underline{\mu(x)}T\mathbf{1}_H T v], \text{ by continuity and isotonicity of } T$ $\leqslant \inf_{v \in \Sigma(x)} \operatorname{hgt}[(\mu T \mathbf{1}_H) T v]$ = $(\mu T \mathbf{1}_H)^-(x).$

That is, $\mu T(\mathbf{1}_H)^- \leq (\mu T \mathbf{1}_H)^-$. \Box

Example 4.1. Let $(X, \overline{}) = (X, \Sigma)$ be a *T*-neighbourhood space and define a function $\Gamma: 2^X \times 2^X \to I$ by

 $\Gamma(\mathbf{1}_H, \mathbf{1}_M) = 1 - hgt[(\mathbf{1}_H)^- T(\mathbf{1}_M)^-], \quad H, M \in 2^X.$

It is easy to verify that the function Γ is a functional *T*-separatedness, it is enough to check (FTS3) and (FTS4) of Theorem 4.1, since the other axioms are trivially hold.

(FTS3) Let $H, M, N \in 2^X$. Then

$$\begin{split} \Gamma(\mathbf{1}_{(H\cup M)}, \mathbf{1}_N) &= 1 - \mathrm{hgt}[(\mathbf{1}_{(H\cup M)})^- T(\mathbf{1}_N)^-] \\ &= 1 - \mathrm{hgt}\{[(\mathbf{1}_H)^- \bigvee (\mathbf{1}_M)^-] T(\mathbf{1}_N)^-] \\ &= 1 - \mathrm{hgt}\{[(\mathbf{1}_H)^- T(\mathbf{1}_N)^-] \bigvee [(\mathbf{1}_M)^- T(\mathbf{1}_N)^-] \} \\ &= 1 - \{\mathrm{hgt}[(\mathbf{1}_H)^- T(\mathbf{1}_N)^-] \bigvee \mathrm{hgt}[(\mathbf{1}_M)^- T(\mathbf{1}_N)^-] \} \\ &= \{1 - \mathrm{hgt}[(\mathbf{1}_H)^- T(\mathbf{1}_N)^-] \} \bigwedge \{1 - \mathrm{hgt}[(\mathbf{1}_M)^- T(\mathbf{1}_N)^-] \} \\ &= \Gamma(\mathbf{1}_H, \mathbf{1}_N) \bigwedge \Gamma(\mathbf{1}_M, \mathbf{1}_N). \end{split}$$

(FTS4) Let $H, M \in 2^X$, with $\Gamma(\mathbf{1}_H, \mathbf{1}_M) > 1 - (\theta T \beta)$ for some $\theta, \beta \in I_0$. Then hgt $[(\mathbf{1}_H)^- T (\mathbf{1}_M)^-] < \theta T \beta$. So, there are $\theta_1, \beta_1 \in I$, such that $\theta_1 < \theta$ and $\beta_1 < \beta$, for which hgt $[(\mathbf{1}_H)^- T (\mathbf{1}_M)^-] < \theta_1 T \beta_1$, hence

$$\emptyset = [(\mathbf{1}_{H})^{-} T(\mathbf{1}_{M})^{-}]_{(\theta_{1}T\beta_{1})*}$$

$$= \bigcup_{\alpha T\gamma \ge \theta_{1}T\beta_{1}} \{ [(\mathbf{1}_{H})^{-}]_{\alpha*} \bigcap [(\mathbf{1}_{M})^{-}]_{\gamma*} \}, \quad \text{by}[4, \text{ Lemma 1.2}]$$

$$\supseteq [(\mathbf{1}_{H})^{-}]_{\theta_{1}*} \bigcap [(\mathbf{1}_{M})^{-}]_{\beta_{1}*}.$$

By taking
$$C = [(\mathbf{1}_M)^-]_{\beta_1*} \in 2^X$$
, we have
 $\Gamma(\mathbf{1}_H, \mathbf{1}_C) = 1 - \operatorname{hgt}[(\mathbf{1}_H)^- T(\mathbf{1}_C)^-]$
 $= 1 - \operatorname{hgt}\{(\mathbf{1}_H)^- T[((\mathbf{1}_M)^-)_{\beta_1*}]^-\}$
 $\ge 1 - \operatorname{hgt}\{(\mathbf{1}_H)^- T[\mathbf{1}_X - ((\mathbf{1}_H)^-)_{\theta_1*}]^-\}$
 $\ge 1 - \operatorname{hgt}\{(\mathbf{1}_H)^- T[\mathbf{1}_X - (\mathbf{1}_H)^-]_{\theta_1*}\}^-, \text{ by Lemma 4.1}$
 $\ge 1 - \operatorname{hgt}(\underline{\theta}_1)^-$
 $= 1 - \theta_1$
 $> 1 - \theta,$

and $\Gamma(\mathbf{1}_{\alpha})$

$$\begin{aligned} & (\mathbf{1}_{(X-C)}, \mathbf{1}_{M}) = 1 - \text{hgt}[(\mathbf{1}_{X-C})^{-} T(\mathbf{1}_{M})^{-}] \\ &= 1 - \text{hgt}\{[\mathbf{1}_{X} - (((\mathbf{1}_{M})^{-})_{\beta_{1}*}]^{-} T(\mathbf{1}_{M})^{-}\} \\ &\geqslant 1 - \text{hgt}\{[\mathbf{1}_{X} - (((\mathbf{1}_{M})^{-})_{\beta_{1}*}]^{-} T(\mathbf{1}_{M})^{-}\}^{-}, \text{ by Lemma 4.1 again} \\ &\geqslant 1 - \text{hgt}(\underline{\beta}_{1})^{-} \\ &= 1 - \beta_{1} \\ &> 1 - \beta. \end{aligned}$$

5. T-proximity induced by T-neighbourhood structure

In this section, we show that every *T*-neighbourhood space generates a *T*-proximity space, also, we introduce the notion of Čech *T*-proximity space. In [1], we have seen that every *T*-uniformity Ω on a set *X*, induces a *T*-proximity $\delta(\Omega)$, we prove that, the *I*-topologies generated by the two structures Ω and $\delta(\Omega)$ are coincide.

Theorem 5.1. Let (X, Σ) be a *T*-neighbourhood space and define $\delta_{\Sigma}: 2^X \times 2^X \to I$ by

$$\delta_{\Sigma}(\mathbf{1}_H, \mathbf{1}_M) = 1 - \Gamma_{\Sigma}(\mathbf{1}_H, \mathbf{1}_M), \quad M, H \in 2^X.$$
(20)

Then δ_{Σ} is a T-proximity on X, also $\tau(\delta_{\Sigma}) \subseteq \Sigma$ and equality holds if and only if (X, Σ) is T-completely regular.

Proof 8. From definition of Γ_{Σ} , we get δ_{Σ} satisfies (TP1), and the other axioms follows immediately from properties of Γ_{Σ} established in Theorem 4.1. Therefore, δ_{Σ} is a *T*-proximity on *X*.

Now, let $M \in 2^X$, $x \in X$ and denote the fuzzy closure operators associated with Σ , $\tau(\delta_{\Sigma})$ and $\tau(\Im)$ respectively by ⁻¹, ⁻², ⁻³. Then, we have

$$\begin{split} [(\mathbf{1}_{M})^{-2}](x) &= \delta_{\Sigma}(\mathbf{1}_{M}, \mathbf{1}_{x}), \quad \text{by } (4) \\ &= 1 - \Gamma_{\Sigma}(\mathbf{1}_{M}, \mathbf{1}_{x}) \\ &= 1 - \{\sup_{f \in \mathfrak{R}(M, x)} [1 - (f(x))(0+)]\} \\ &= \inf_{f \in \mathfrak{R}(M, x)} (f(x))(0+) \\ &= \inf_{f \in \mathfrak{R}(M, x)} (f(\mathbf{1}_{M})]^{-3})(f(x)), \quad \text{by Proposition 3.2} \\ &\geqslant \inf_{f \in \mathfrak{R}(M, x)} [f((\mathbf{1}_{M})^{-1})](f(x)), \quad \text{by continuity of } f \\ &= \inf_{f \in \mathfrak{R}(M, x)} [f^{-}(f((\mathbf{1}_{M})^{-1}))](x) \\ &\geqslant [(\mathbf{1}_{M})^{-1}](x), \quad \text{clear} \end{split}$$

Which yields,

$$(\mathbf{1}_M)^{-2} \ge (\mathbf{1}_M)^{-1}, \quad \forall \ M \in 2^X.$$

$$(21)$$

This establishes (cf. [5. Corollary 2.1]) that, $\tau(\delta_{\Sigma})$ is coarser than Σ .

On the other hand, if (X, Σ) is *T*-completely regular, then by Theorem 3.2, we get for every $M \in 2^X$, $x \in X$ and $\theta \in I_0$, there is a continuous function

 $g: (X, {}^{-}) \to (\mathcal{D}^+, \tau(\mathfrak{I})),$ for which $g(M) = \varepsilon_0$ and $(g(x))(0+) < (\mathbf{1}_M)^-(x) + \theta,$ (that is $g \in \mathfrak{R}(M, x)$). Consequently

$$[(\mathbf{1}_{M})^{-2}](x) = \delta_{\Sigma}(\mathbf{1}_{M}, \mathbf{1}_{x})$$

= 1 - $\Gamma_{\Sigma}(\mathbf{1}_{M}, \mathbf{1}_{x})$
= 1 - { $\sup_{f \in \Re(M, x)} [1 - (f(x))(0+)]$ }
 $\leq \inf_{f \in \Re(M, x)} (f(x))(0+)$
 $\leq (g(x))(0+)$
 $\leq [(\mathbf{1}_{M})^{-1}](x) + \theta.$

This yields,

$$(\mathbf{1}_M)^{-2} \leqslant (\mathbf{1}_M)^{-1}, \quad \forall \ M \in 2^X$$

This establishes the opposite inequality (21), which renders $\tau(\delta_{\Sigma}) = \Sigma$.

Conversely, if $\tau(\delta_{\Sigma}) = \Sigma$ then Σ is *T*-proximizable, and hence *T*-completely regular.

As in [2], since the *I*-topological space $(X, \tau(\delta))$ induced by the *T*-proximity space (X, δ) is a *T*-neighbourhood space, then from this fact together with Theorem 5.1, we have there is a one to one corresponding between *T*-proximity and *T*-neighbourhood structures. \Box

Definition 5.1. If the *T*-neighbourhood space (X, Σ) is a *T*-completely regular, then the *T*-proximity δ_{Σ} on *X*, defined by (20), is called Čech *T*-proximity of (X, Σ) .

To justify this terminology, we proceed to establish a maximality property for Čech *T*-proximities.

Theorem 5.2. The Čech T-proximity δ_{Σ} , of a T-completely regular T-neighbourhood space (X, Σ) , is the finest T-proximity on X that induces Σ .

Proof 9. By Theorem 5.1, we have δ_{Σ} induces Σ . Now, let δ be another *T*-proximity on *X* that induces Σ . For all nonempty subsets *H*, *M* of *X*, and all $\alpha > \delta(\mathbf{1}_H, \mathbf{1}_M)$, there is, by Proposition 3.5, a function $f \in \mathfrak{R}(H, M)$ with (f(M)) (1) = α . Consequently, $\delta_{\Sigma}(\mathbf{1}_H, \mathbf{1}_M) = 1 - \Gamma_{\Sigma}(\mathbf{1}_H, \mathbf{1}_M) \leq (f(M))(0+) \leq (f(M))(1) = \alpha$.

This establishes $\delta(\mathbf{1}_H, \mathbf{1}_M) \ge \delta_{\Sigma}(\mathbf{1}_H, \mathbf{1}_M)$, which proves that δ is coarser than δ_{Σ} . \Box

Theorem 5.3. Let $f: (X, \delta) \rightarrow (Y, \rho)$ be a proximally continuous function. Then it is continuous with respect to the *I*-topologies generated by δ and ρ , respectively.

Proof 10. We denote the fuzzy closure operators associated with $\tau(\delta)$ and $\tau(\rho)$ respectively by $^{-1}$, $^{-2}$. Then, for every $\lambda \in I^X$ and all $y \in Y$, we have

$$[f(\lambda^{-1})](y) = \sup_{x \in f^{-}(y)} (\lambda^{-1})(x)$$

$$= \sup_{x \in f^{-}(y)} \delta(\lambda, \mathbf{1}_{x}), \quad \text{by (4)}$$

$$\leq \sup_{x \in f^{-}(y)} \rho(f(\lambda), f(\mathbf{1}_{x})), \quad \text{by hypothesis}$$

$$= \sup_{x \in f^{-}(y)} \rho(f(\lambda), \mathbf{1}_{f(x)})$$

$$= \sup_{x \in f^{-}(y)} [f(\lambda)]^{-2}(f(x))$$

$$= [f(\lambda)]^{-2}(y),$$

that is, $f(\lambda^{-1}) \leq [f(\lambda)]^{-2}$

Which proves the continuity of $f: (X, \tau(\delta)) \to (Y, \tau(\rho))$. \Box

Proposition 5.1. If the function $f: (X, \Sigma) \to (Y, \Sigma')$ between *T*-neighbourhood spaces is continuous, then it is a proximally continuous from (X, δ_{Σ}) to $(Y, \delta_{\Sigma'})$. The converse holds when its codomain (Y, Σ') is *T*-completely regular.

Proof 11. For all nonempty $H, M \in 2^X$ and all $g \in \mathfrak{R}_{\Sigma'}(f(H), (f(M)))$, the composite function g o f is in $\mathfrak{R}_{\Sigma}(H, M)$. This entails that

$$\begin{split} \delta_{\Sigma}(\mathbf{1}_{H},\mathbf{1}_{M}) &= 1 - \Gamma_{\Sigma}(\mathbf{1}_{H},\mathbf{1}_{M}) \\ &\leq 1 - \Gamma_{\Sigma'}(\mathbf{1}_{f(H)},\mathbf{1}_{f(M)}) \\ &= \delta_{\Sigma'}(\mathbf{1}_{f(H)},\mathbf{1}_{f(M)}) \\ &= \delta_{\Sigma'}(f(\mathbf{1}_{H}),f(\mathbf{1}_{M})). \end{split}$$

Hence, by (2), we have f is a proximally continuous with respect to δ_{Σ} and $\delta_{\Sigma'}$.

Conversely, suppose that $h: (X, \delta_{\Sigma}) \to (Y, \delta_{\Sigma'})$ is a proximally continuous, then, by Theorem 5.3, we get $h: (X, \tau(\delta_{\Sigma})) \to (Y, \tau(\delta_{\Sigma'}))$ is continuous.

But from Theorem 5.1, we have $\tau(\delta_{\Sigma}) \subseteq \Sigma$ and $\tau(\delta_{\Sigma'}) = \Sigma'$, consequently,

h is also continuous: $(X, \Sigma) \rightarrow (Y, \Sigma')$.

Now, we define a function δ^{\sim} , from category of *T*-neighbourhood spaces and continuous functions to category of *T*-proximity spaces and proximally continuous functions, as:

On object (X, Σ) in *T*-NS, by $\delta^{\sim}(X, \Sigma) = (X, \delta_{\Sigma})$ an objects in *T*-PS. On morphisms, δ^{\sim} is the identity function. Then an obvious conclusion from the above theorems is that these δ^{\sim} is well defined functor. \Box

Proposition 5.2. [2]*Let* (X, Ω) *be a T-uniform space. Then the fuzzy closure operator of the T-neighbourhood space* $(X, \tau(\Omega))$ *is given by:*

$$\mu^- = \inf_{\psi \in \Omega} \psi \langle \mu \rangle_T, \quad \mu \in I^X.$$

Theorem 5.4. If Ω is a *T*-uniformity on a set *X*, and $\delta(\Omega)$ is the *T*-proximity induced by the *T*-uniformity Ω , then the *I*-topology $\tau(\Omega)$ coincide with $\tau(\delta(\Omega))$.

Proof 12. Let $\mu \in I^X$ and $x \in X$, and denote the fuzzy closure operators associated with $\tau(\Omega)$ and $\tau(\delta(\Omega))$ respectively by ⁻¹, ⁻². Then, we have

$$\mu^{-2}(x) = (\delta(\Omega))(\mu, \mathbf{1}_x), \text{ by } (4)$$

= $(\delta(\Omega))(\mathbf{1}_x, \mu), \text{ by } (\text{TP2})$
= $\inf_{\psi \in \Omega} \sup_{y \in X} (\mathbf{1}_x, T\psi \langle \mu \rangle_T)(y), \text{ by } (3)$
= $\inf_{\psi \in \Omega} (\psi \langle \mu \rangle_T)(x)$
= $\mu^{-1}(x), \text{ by Proposition 5.2}$

This proves our assertion. \Box

Proposition 5.3 1. If Ω_{δ} is the *T*-uniformity induced by a *T*-proximity δ on a set *X*, then $\delta(\Omega_{\delta}) = \delta$. By combining Theorem 5.4 and Proposition 5.3, we arrive to the fact that, a *T*-proximizability is equivalent to *T*-uniformizability. Hence, from Theorem 3.2, we get a *T*-neighbourhood space is *T*-proximizable (i.e., induced by a *T*-proximity) if and only if it is *T*-completely regular.

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